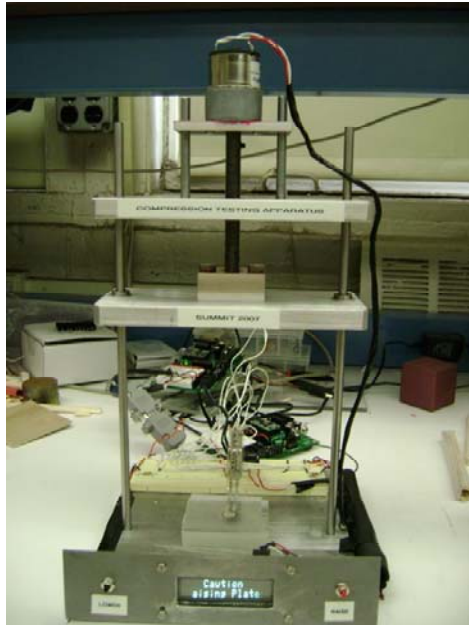


Compression Testing Apparatus



by

Sabah Ayoub & Lindrick Outerbridge

Professor Vikran Kapila

OUTLINE

- 1- Abstract
- 2- Introduction
- 3- Background information
 - 1- type of bridges
 - 2- forces acting on bridges
- 5-Material used
- 6-Experiment
 - 3- The device
 - 4- Electrical circuit
- 7-How its work
- 8-Computer program
- 9-Results
- 10-Conclusion
- 11Future work
- 12-Activities
- 13-Curriculum correlation: standards
 - 1- Physics
 - 2- Technology
 - 3- Interdisciplinary
- 14- Acknowledgements
- 15- References

SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

1-Abstract

The intent of this project is to provide students with a visual demonstration of material tested for compression. This demonstration will be used in technology and physical science classes. The use of electrical part, mechanical parts and computer programming will also provide more interdisciplinary lessons.

2-Introduction

Who among us, really, hasn't crossed a bridge and at least paused over the disconcerting possibility that the structure might collapse into free fall?

“A 600-foot section of an interstate bridge over the Arkansas River collapsed on May 26, 2007 when one of two barges going north on the river rammed a pylon. About a dozen vehicles plunged into the river. Five people were rescued from the water, but authorities are certain that there were fatalities.”

“Late July 2007, a 40-year-old interstate highway bridge collapsed in Minneapolis, plunging rush-hour traffic into the Mississippi River 60 feet below.”

Truss bridges such as the one in Minneapolis, whose pillars carry loads by tension and compression, long have been the workhorses. They were invented in America to span wide waterways, the Mississippi in particular, and this is the big question today in Minneapolis. Why did the bridge collapse?

While bridge collapses are rare, they remain spectacular and have a lasting impact on people' minds.

As a minimum, the goal is to break that chain of failures by conducting a proactive research program that provides solutions that can be implemented prior to the catastrophic failure. The key to avoid future horrific circumstances will be the use of advanced or enhanced materials, inspection technology, design procedures, construction methods, operational practices, maintenance and rehabilitation technology, and management techniques. We must use technology that permits to test, during the design stage of the bridge, all beams and columns susceptible to keep the bridge safe and stable. The challenge to develop and implement this technology must be undertaken in partnership with the entire highway community -- government at all levels, universities, highway users, the construction industry, and heavy vehicle manufacturers.

In our summer project with Summit at Polytechnic Institute, as a team, we have opted for an apparatus that will detect and display the maximum force structural material undergoes. Selection for this project falls well into our study scope, as we teach students physics and technology. Both have agreed this venture will benefit our student population back in our schools.

The compression apparatus determines the equilibrium force, which is the maximum load a structural element as a beam or a column can sustain. Loads may include the weight of truck

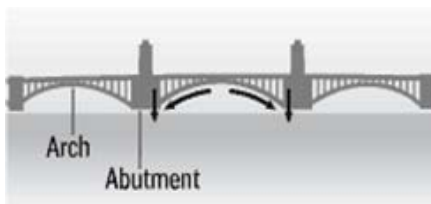
SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

and cars in motion, force of the wind, weight of snow, our compression apparatus is operated in association with a two platen parts which one can move relative to one another. The compression apparatus is formed of at least one compression units having a working chamber and a working element which can move in it.

3-- Background information

They are many types of bridges all over the world. What make them different will depend on their purpose, location, environment, length of span, material they are made of and their cost. The most common bridges are:

1- Type of bridges



Arch bridges are the earliest one



Beam bridges are the simplest one.



Cable bridges are used for medium span.

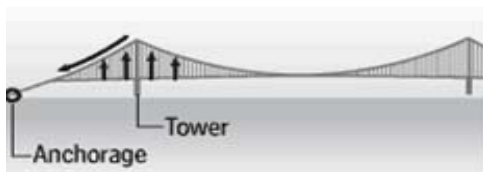


Used to span great distance



Tcmilinson Litt Bridge

They can open to allow boat to go through



Have the longest span distance

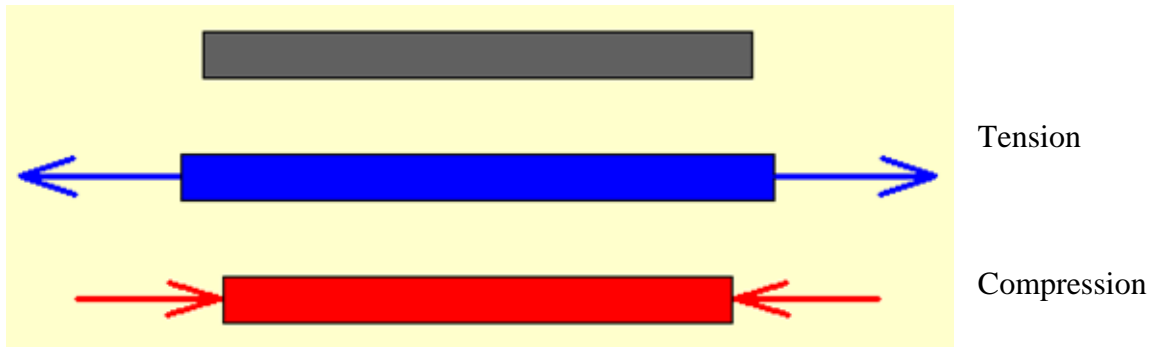
SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

2- Forces acting on bridges:

When designing and constructing a bridge, engineers have to consider many factors. They need to know which material and structure is best for a stable bridge? Many forces act on a bridge. The two most important one are tension and compression bridges.

Compression is a force that acts to compress or shorten the object it is acting on.

Tension is the force that acts to extend or expend the object it is acting on



Material can have both tension and compression applied at the same time .A good examples of these are bridges.

In any static structure such as bridges they will be forces acting on it at any point. These forces need to be in equilibrium.

The blue arrows represent tension

The red arrows represent compression

The green arrows represent force of gravity



SUMMIT: SUMmer Mechatronics Institute for Teachers 2007



The structural members of a bridge will react to those acting on them by producing internal forces. They do this by deflecting until the forces they generate balance the one applied on them. If a member reaches its limit of strength before the necessary force is attained, it will bend, snap, twist or break. It is the task of the bridge designer to analyze and study these forces in order to avoid buckling or snapping. Buckling is what happens when the force of compression overcomes an object's ability to handle compression, and snapping is what happens when the force of tension overcomes an object's ability to handle tension

SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

Minneapolis Mississippi Bridge I-35w

The bridge collapse during Minneapolis Rush hour on Wednesday 08-01-07 has raised questions about structural problem

BEFORE



AFTER



SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

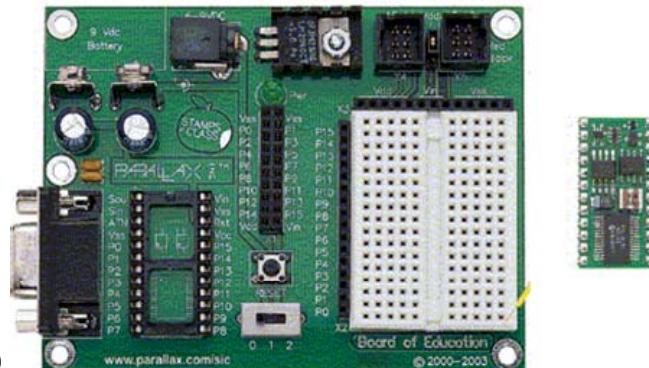
Our project is to build a device (compression testing apparatus) that will simulate how materials are tested for their ability to resist compression.

4 Material used;

1- flexi Force:

Flexi force sensor and the capacitor are the basic tools in this project.

Flexi Force measures compression exerted versus resistance. The resistance of flexi force is proportional to weight .



2-Board of education (BOE)

The board of education supplies a regulated +5volts (Vdd) and ground (Vss) as well as a small breadboard for circuit and connector to 16 pins.

3- Piezo Speaker: used as a signal to stat a program



SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

4-motor: used to move the movable piston up a down



5-push button: used to start and stop the program

6-capacitor: is connected to the flexi force



7- Pololu motor micro controller: can independently set motor to go forward or backward.

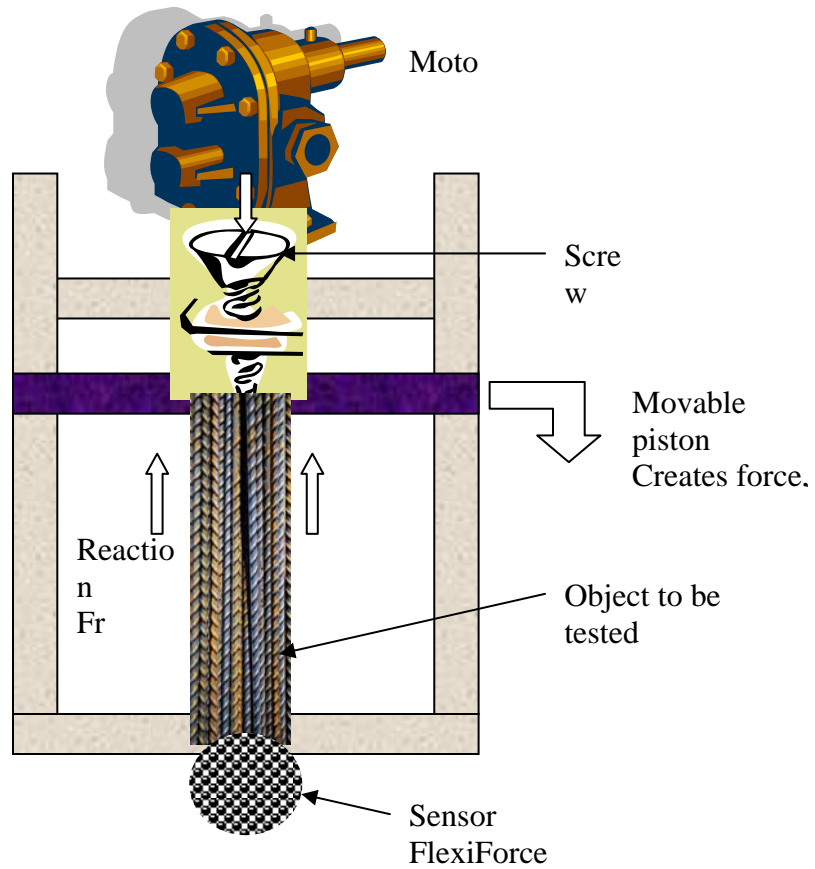


8-Parallax serial LCD: provides basic text wrapping on the display



5-Experiment

1-The device



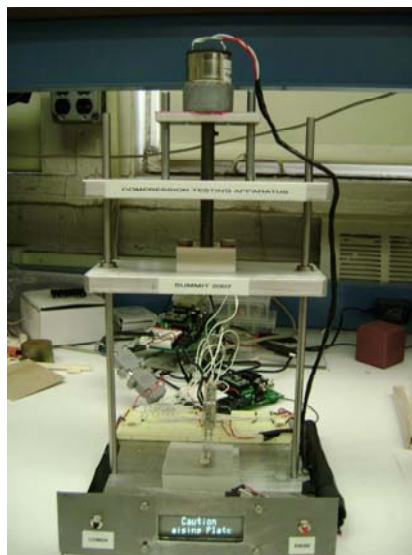
Compression testing apparatus

At equilibrium:

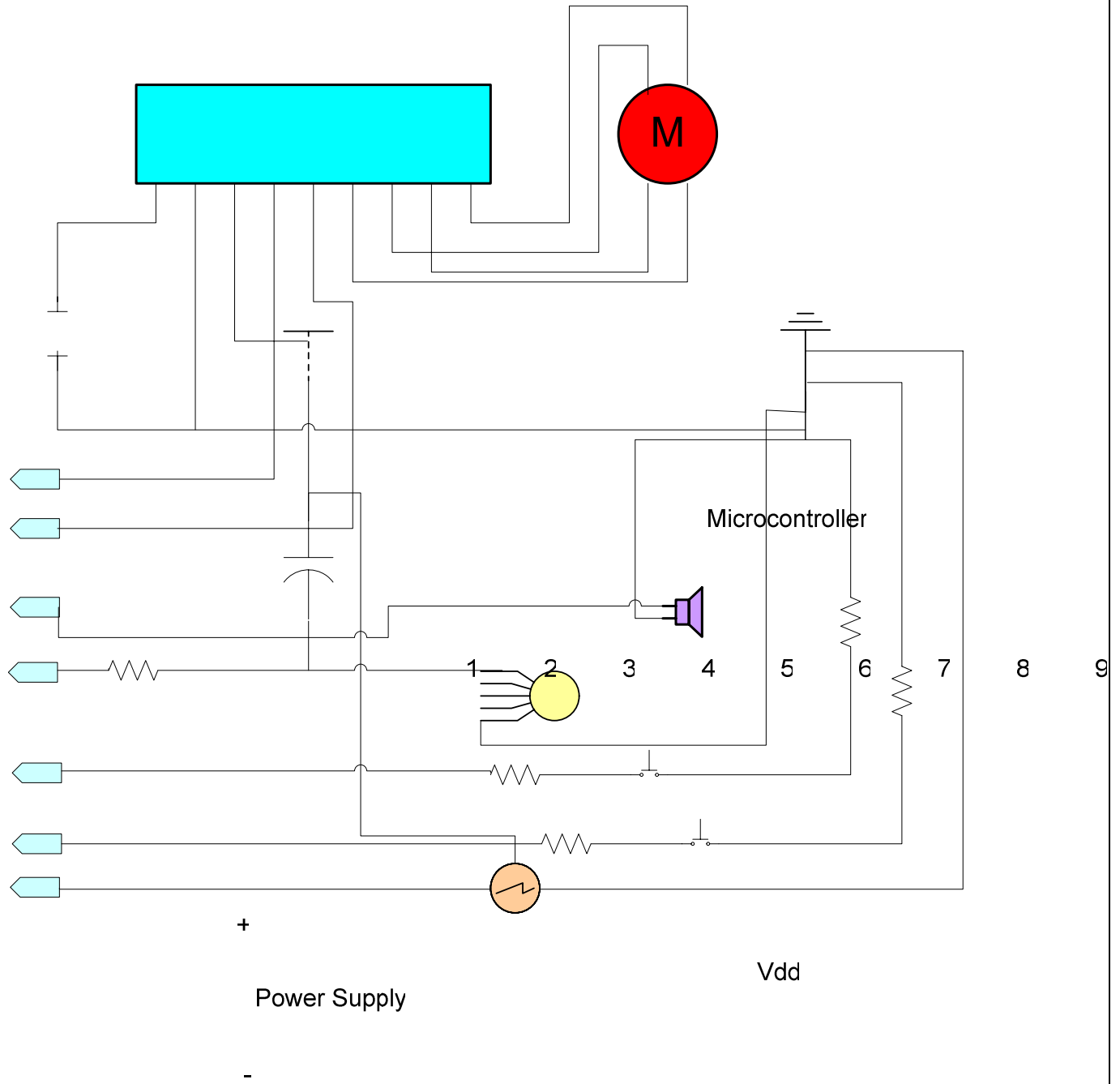
Force $F =$ Force F_r

IF FORCE $F >$ REACTION FORCE F_r the object will buckle.

**Compression testing
Apparatus model
Design**



2--Electrical circuit



SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

6- Computer Program

```
' Compression Testing Machine - CompressionMachine.bs2
' Progrsm Listing
' Programmers: Lindrick Outerbridge
' Sabah
' {$STAMP BS2}
' {$PBASIC 2.5}
' -----[ Revision History ]-----
' 8/1/07
' 8/9/07 VFD Display shows realtime force values. Shows greatest value at the
end.
' -----[ Declarations ]-----

rawForce      VAR      Word      ' Stores raw output
sensorPin     CON      1          ' Flexiforce sensor circuit
calibration   CON      6000      ' Calibration raw Flexiforce equivalent to 1
kg mass
calibtimesgrav CON      58860    ' calibration times 9.81 gravity constant
counter       VAR      Word
ForceInteger  VAR      Byte
ForceDecimal  VAR      Byte
speed         VAR      Byte      ' DC motor speed
Force         VAR      Byte
LargestForce  VAR      Byte
LFInteger     VAR      Byte
LFDecimal     VAR      Byte
' -----[ I/O Definitions ]-----

VFD           PIN      5          'VFD Serial I/O PIN

' ***** CHECK YOUR WIRING BEFORE POWERING UP THE VFD *****

' -----[ Constants ]-----

Baud          CON      6          ' 38.4 Kbps (BS2)

' These are constants for common control characters on the display.
' Remember, some are already defined in the editor, like CR and LF.

BS            CON      $08       ' Back Space
HT            CON      $09       ' Horizontal Tab
HOM           CON      $0B       ' Home Position
CLR           CON      $0C       ' Display Clear

' -----[ Variables ]-----

index         VAR      Byte      ' Index Variable

' -----[ Initialization ]-----

HIGH VFD      ' Initialize I/O Pin
PAUSE 200     ' Allow Time To Settle
```

SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

```
' This command resets the display settings to default values, but the input
' buffer is not affected (contents remain).
```

```
SEROUT VFD, Baud, [$1B, $40, $0C]      ' Initialize Display
PAUSE 200                               ' Allow Time To Settle
```

```
' You need to set this if you plan to write to the non-visible display
' memory. Write Screen Mode Select: 0=Display Screen, 1=All Screen
```

```
SEROUT VFD, Baud, [$1F, $28, $77, $10, $01]
' This digit is the one to change      ^^
```

```
' -----[ Program Code ]-----
```

Main:

```
SEROUT VFD, Baud, ["Compression Test", CR, LF, " Apparatus"] ' Title
Screen
```

```
PAUSE 3000
```

```
SEROUT VFD, Baud, [CLR]                ' Clear The Display
```

```
SEROUT VFD, Baud, ["Outerbridge, L.", CR, LF, " Sabah Ayoub"]
```

```
PAUSE 2000
```

```
DO
```

```
GOSUB Display_On_Off                    ' Do Display On/Off Demo
```

```
GOSUB Wait_For_Start                    ' Do Wait for Button Press
```

```
LOOP                                     ' Loop Forever
```

```
' -----[ Subroutines ]-----
```

Display_On_Off:

```
SEROUT VFD, Baud, [CLR]                ' Clear The Display
```

```
SEROUT VFD, Baud, [" SUMMIT 2007", CR, LF, " PolyTechnic U."]
```

```
PAUSE 2000
```

```
RETURN
```

```
' -----
```

Wait_For_Start:

```
' Prepare motor for operation
```

```
HIGH 2                                  ' take serial line high
```

```
LOW 3                                   ' reset motor controller
```

```
HIGH 3
```

```
PAUSE 100                               ' motor controller startup time
```

```
SEROUT VFD, Baud, [CLR]                ' Clear The Display
```

```
SEROUT VFD, Baud, ["Model CTA-OA-07 ", CR, LF, "START ADJUST"]
```

```
LargestForce = 0
```

```
DO
```

```
LOOP UNTIL IN0 = 1 OR IN4 = 1          ' wait for any button press
```

```
IF IN0 = 1 THEN ' Start compression testing
```

```
GOSUB Start_Machine
```

```
RETURN
```

```
ENDIF
```

SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

```
IF IN4 = 1 THEN      ' Config mode to adjust height
  SEROUT VFD, Baud, [CLR]          ' Clear The Display
  SEROUT VFD, Baud, [" Load Length", CR, LF, "LOWER      RAISE"]
  PAUSE 100
  DO
  LOOP UNTIL IN0 = 1 OR IN4 = 1
  FREQOUT 6, 200, 2000  ' Beep sound
IF IN0 = 1 THEN      ' move down until black button is pressed again
  FREQOUT 6, 200, 2000  ' Beep sound
  SEROUT VFD, Baud, [CLR]          ' Clear The Display
  SEROUT VFD, Baud, [" Caution", CR, LF, "Lowering Plates"]
  DO
    SEROUT 2,84,[$80, 0, 1,127]
    PAUSE 20
  LOOP UNTIL IN0 = 1
  FREQOUT 6, 200, 2000  ' Beep sound
ENDIF

IF IN4 = 1 THEN      ' move up until red button is pressed again

  FREQOUT 6, 200, 2000  ' Beep sound
  SEROUT VFD, Baud, [CLR]          ' Clear The Display
  SEROUT VFD, Baud, [" Caution", CR, LF, " Raising Plates"]
  DO
    SEROUT 2,84,[$80, 0, 0,127]
    PAUSE 20
  LOOP UNTIL IN4 = 1
  FREQOUT 6, 200, 2000  ' Beep sound

ENDIF

RETURN
ENDIF

DEBUG CLS
RETURN
```

' -----
Start_Machine:

```
LargestForce = 1
' Starting Sound - a beep
FREQOUT 6, 200, 2000
' Run Motor
HIGH 2          ' take serial line high
LOW 3           ' reset motor controller
HIGH 3
PAUSE 100      ' motor controller startup time

' Apparatus is engaged - Caution!
SEROUT VFD, Baud, [CLR]          ' Clear The Display
SEROUT VFD, Baud, ["Keep Clear", CR, LF, "At All Times"]
DO
  ' Read FlexiForce Sensor
  HIGH sensorPin                ' Discharge the capacitor
```

SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

```
PAUSE 2
RCTIME sensorPin,1,rawForce          ' Measure RC charge time

DEBUG "Flexiforce raw output = ", DEC rawForce,CR
SEROUT VFD, Baud, [CLR]              ' Clear The Display

Force = calibtimesgrav / rawforce
ForceInteger = Force
ForceDecimal = (calibtimesgrav) // rawforce
IF ForceInteger > LargestForce THEN
DEBUG "hello"
    LargestForce = ForceInteger
    LFInteger = ForceInteger
    LFDecimal = ForceDecimal
ENDIF
SEROUT VFD,Baud, ["Specimen Testing:",CR,LF]
SEROUT VFD, Baud, [DEC3 ForceInteger,".", DEC2 ForceDecimal,"N"]
SEROUT 2,84,[$80, 0, 1,50]
PAUSE 20
LOOP UNTIL IN0 = 1
FREQOUT 6, 200, 2000 ' Beep sound
' Slow motor down to complete stop
    FOR speed = 127 TO 0
        SEROUT 2,84,[$80, 0, 0,speed]
        PAUSE 20
    NEXT
SEROUT VFD, Baud, [CLR]
SEROUT VFD,Baud, ["Max. Strength:",CR,LF]
SEROUT VFD, Baud, [DEC3 LFInteger,".", DEC2 LFDecimal,"N"]

PAUSE 5000
DO
LOOP UNTIL (IN0 = 1 OR IN4 = 1)
FREQOUT 6, 200, 2000 ' Beep sound

RETURN

' -----
```

SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

7-How it works:

The flexi force which is connected to a capacitor acts like a resistor. When the sensor is unloaded its resistance is very high (the rctime will be low). When a force is applied to the sensor, its resistance decreases (the rctime will be).

The computer will read the input from the flexi force as raw number. A command in the programming will change this raw number into a Newton. Using a the rctime of a known mass (in our case 1 Kg)

The black push button starts the motor that will rotate forward turning the screw the pushes the piston down.

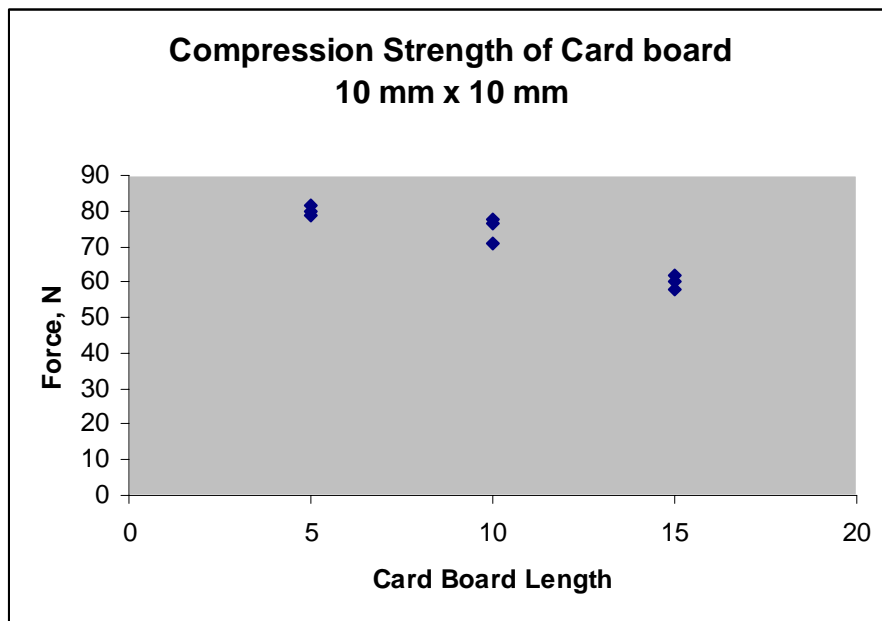
The red push button will end the program and will make the motor rotate backward making the piston go up.

The motor that is controlled by the microcontroller will increase the compression on the load (object tested) until the object buckles.

The result (the highest compression) is displayed in the LCD

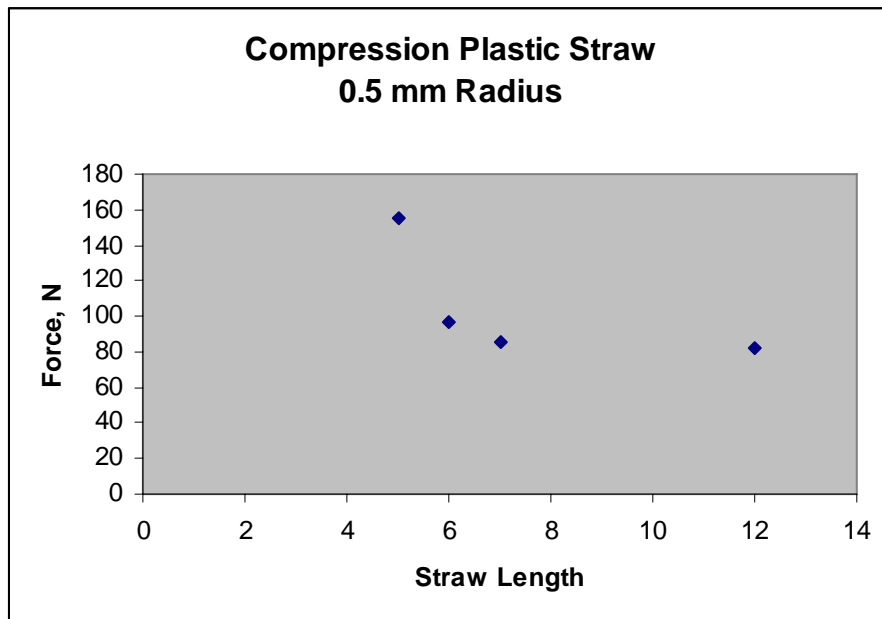
8-Results

Test Number	Size	Length	Compressive Strength
	(mm)	(cm)	(N)
C1	10 x 10	5	79.63
C1	10 x 10	5	78.48
C1	10 x 10	5	81.54
C2	10 x 10	10	70.71
C2	10 x 10	10	77.84
C2	10 x 10	10	76.72
C3	10 x 10	15	60.2
C3	10 x 10	15	62.15
C3	10 x 10	15	58.12
C4	6 x 10	5	
C4	6 x 10	5	
C4	6 x 10	5	
C5	6 x 10	10	39.55
C5	6 x 10	10	
C5	6 x 10	10	
C6	6 x 10	15	
C6	6 x 10	15	
C6	6 x 10	15	



SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

Plastic Straws	Radius	Length	
	cm	cm	
circular	0.5	5	155.14
circular	0.5	6	96.4
circular	0.5	7	85.38
circular	0.5	12	82.42
Triangle		6	32.7
Triangle		12	11.97
Wood	Radius	Length	
circular	0.5	6	52.4
Triangle		6	36.5



SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

9- Conclusion

Throughout this project, our goal was to provide students with a visual demonstration of the procedure engineers use to test materials for their strength using a compressor. Our compression testing apparatus is a smaller scale model that operates and replicates what actual compressors run and test in the industry standards. We believe this experiment conducted in our school lab will confer our students with clear idea of the actual procedures, and hence will help them make decisions and planning regarding their what-about their would be exposed later if they were to opt for this rapidly growing engineering field.

10--Future work

Design a device that will test how much an object can extend (measure tension) and see if there is any type of relation between the compression and the tension of a same object

11-Activities

- 1- Explain that when forces on an object are balanced, the motion of the object does not change.
- 2- Identify all the forces acting on a single object.
- 3- Determine what factors need to be considered in building stable object.
- 4- Determine what structure is more suitable for building a stable bridge.
- 5- Compare and contract the pros and the cons of various bridge building materials.
- 6- Draw a graph.
- 7- Newton third law of motion : for every action there is an equal and opposite reaction
- 8- Analyze data

SUMMIT: SUMmer Mechatronics Institute for Teachers 2007

12-Curriculum Correlation: NY State standards

1-PHYSICS

STANDARD 4: investigate the use of common forces (push and pull) on objects.

Standards 5: matter is made up of particles whose properties determine the observable characteristics of matter and its reactivity

2--Technology:

Standard 5: students will apply technology knowledge and skills to design, construct, use and evaluate product and systems to satisfy human and environmental needs

3-Interdisciplinary

Standard 6: students will understand the relationships and common themes that connect mathematics, science and technology.

Standard 7: student will use the knowledge of thinking skill of mathematics, science and technology to address real life problems and make informed decisions.

ACKNOWLEDGEMENTS

We would like to thank the following persons for their guidance throughout this project

Sang Hoon (Nathan)LEE

Anshuman Panda

Padmini Vijayakumar

Kwokkei(Keith)Ching

Jared Frank

Billy Mark

Shing Lik Wong

and special thanks for Danial Remiszewski for his support and patience and Professor Vikram Kapila for his overall assistance

References

- 1- 32.brinkster.com
- 2- Glenbrook.k12.il.us/GBSSCI/physic.
- 3- www.En.wikipedia.org/wiki/surface
- 4- Parallax.com
- 5- www.popolu.com
- 6- www.stampsinclass.com
- 7- What is a microcontroller .by Andy Lindsay. Version 2.2
- 8- Basic stamp syntax and reference manual version 2.2
- 9-