

# Glove controlled Wheelchair

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# Wheelchairs



Roughly 3.6 million people(aged 15 or older) are using a wheelchair

Using a manual wheelchair can cause repetitive strain injury, Mostly shoulder and wrist

# Electric Wheelchair

- Electric Wheelchair was invented in early 1900s
- Conventional Control - Joystick control



# Controlled by Fingers

Gloves that is attached with flex sensors

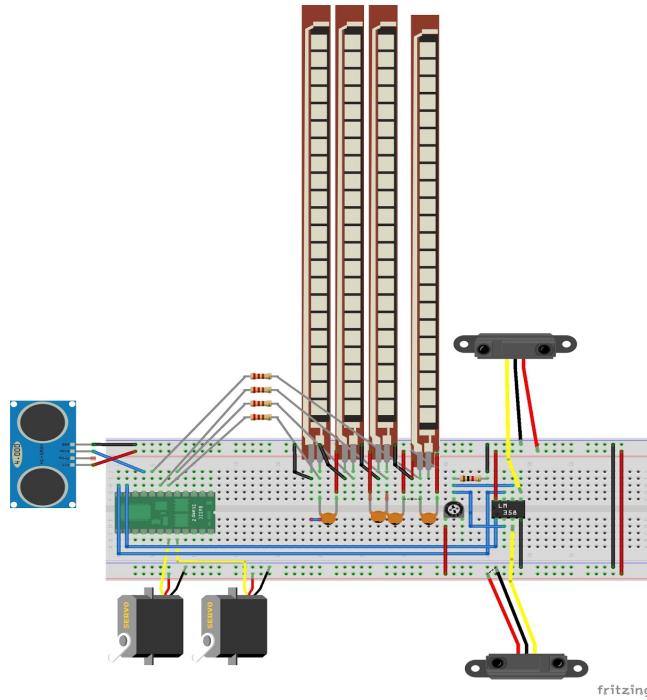
Read movement of fingers to control motion of wheelchairs



```
'Flex Sensor1
F1:
    HIGH 0 'hold pin 0 high to charge capacitor
    PAUSE 1 'charge capacitor for 1/1000 of a second
    RCTIME 0, 1,fs1 'measure discharge time of flex resistor through capacitor
    'fs1=fs1**scalecon1+500
    temp = fs1*439 - 2572
    fs1 = fs1 - temp
    fs1 = fs1/2

RETURN
```

# Circuit Diagram



# Why not go further?

## Ultrasonic sensor

- It will detect an obstacle in front of the wheelchair



```
DO WHILE (ul1 < 20)
    PULSOUT LeftServo, 750
    PULSOUT RightServo, 750
    DEBUG CR,"STOP UltraSonic"
    SEROUT lcd, 84, [12]
    PAUSE 5
    SEROUT lcd, 84, [128,"STOP2 Ultrasonic"]
    PAUSE 10

    GOSUB ping
    PAUSE 20
LOOP
```

# Cliff Detector

IR-sensor

Detect the back and the front cliff.



'IR sensor

IRS:

DO WHILE (IN6 = 0) OR (IN7 = 0)

PULSOUT LeftServo, 750

PULSOUT RightServo, 750

DEBUG CR, "STOP IR Sensor"

SEROUT lcd, 84, [12]

PAUSE 5

SEROUT lcd, 84, [128, "CLIFF DETECTED"]

PAUSE 5

PAUSE 20

LOOP

'Check for IR Sensor 1 and 2 HIGH

' Left Servo Move Pulse Value

' Right Servo Move Pulse Value

# How to interface with User?

Monitor the statues of  
wheelchair

- Forward
- Back
- Right
- Left
- Stationary
- Cliff Detected etc..



# Safety

Two fingers movement  
(here 3 and 4) will stop the  
motion of wheelchair and  
put it in suspended mode.

```
IF (fs3 < 450) AND (fs4 < 450) THEN  'Stop switch
DO
  IF(fs2 < 450) AND (fs1 < 450) THEN  'Reset the stop switch
    SEROUT lcd, 84, [12]
    PAUSE 5
    SEROUT lcd, 84, [128,"Reset Cleared"]
    PAUSE 5
    DEBUG "reset cleared"
    GOTO main
  ELSE
    DEBUG "reset"
    SEROUT lcd, 84, [12]
    PAUSE 5
    SEROUT lcd, 84, [128,"STOP1 Switch"]
    PAUSE 5
    GOSUB f3
    GOSUB f4
  ENDIF
  LOOP
ENDIF
```

# Bill of Material

Bill of Material for Mechatronics Term Project				
Item	Cost per Item	No of Item	Total	Mass Production
Flex Sensor	7.49	4	29.96	20
IR Sensor	12	2	24	16
Wires	3	3	9	3
Ultrasonic	15	1	15	12
Boebot Chasis	59	1	59	40
Total			136.96	91

# Advantage and Disadvantage

## - Pros

- People who have RSI on their wrist can control wheelchair easily
- Wearable
- It can use as little as two and at most four fingers so the system can be customized for different users.

## - Cons

- The glove is wired so it is clunky and obtrusive

# References

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**THANK YOU**