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# Glove controlled Wheelchair

Parth Singh  
Sungyoung Kim  
Ishan Darji





# Table

1. Introduction
2. Issues and Resolution
3. Components and Code
4. Test run



# Wheelchairs



Roughly 3.6 million people(aged 15 or older) are using a wheelchair

Using a manual wheelchair can cause repetitive strain injury, Mostly shoulder and wrist



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# Electric Wheelchair

- Electric Wheelchair was invented in early 1900s
- Conventional Control - Joystick control



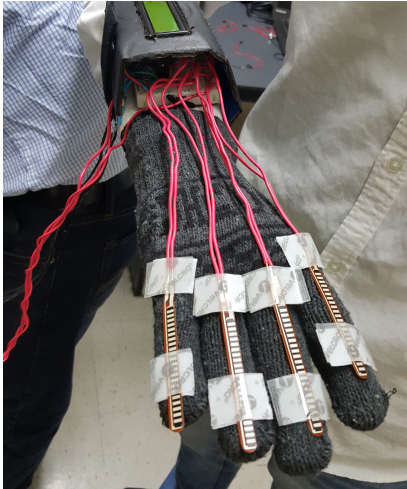




# Controlled by Fingers

Gloves that is attached with flex sensors

Read movement of fingers to control  
motion of wheelchairs

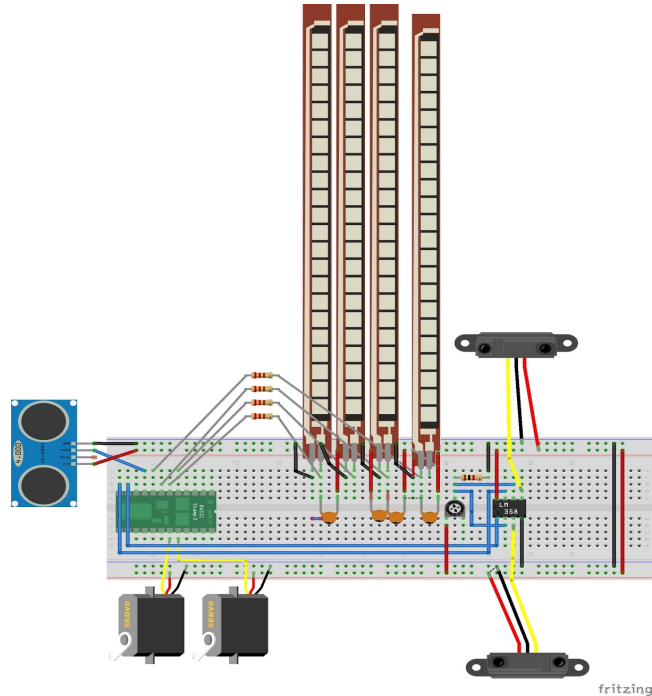


```
'Flex Sensor1
F1:
  HIGH 0 'hold pin 0 high to charge capacitor
  PAUSE 1 'charge capacitor for 1/1000 of a second
  RCTIME 0, 1, fs1 'measure discharge time of flex resistor through capacitor
  'fs1=fs1**scalecon1+500
  temp = fs1*/439 - 2572
  fs1 = fs1 - temp
  fs1 = fs1/2

RETURN
```



# Circuit Diagram





# Why not go further?

## Ultrasonic sensor

- It will detect an obstacle in front of the wheelchair



```
DO WHILE (u11 < 20)                                'Obstacle detection
PULSOUT LeftServo, 750                               ' Left Servo Move Pulse Value
PULSOUT RightServo, 750                             ' Right Servo Move Pulse Value
DEBUG CR,"STOP UltraSonic"
SEROUT lcd, 84, [12]
PAUSE 5
SEROUT lcd, 84, [128,"STOP2 UltraSonic"]
PAUSE 10

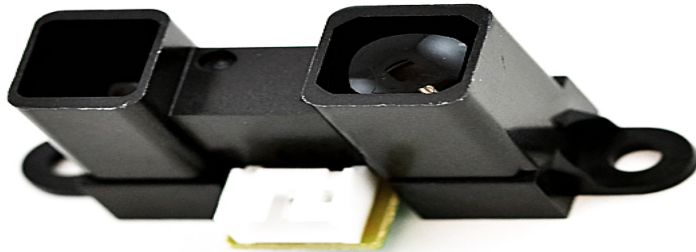
GOSUB ping
PAUSE 20
LOOP
```



# Cliff Detector

IR-sensor

Detect the back and the front cliff.



```
'IR sensor
```

```
IRS:
```

```
DO WHILE (IN6 = 0) OR (IN7 = 0)
```

```
PULSOUT LeftServo, 750
```

```
PULSOUT RightServo, 750
```

```
DEBUG CR, "STOP IR Sensor"
```

```
SEROUT lcd, 84, [12]
```

```
PAUSE 5
```

```
SEROUT lcd, 84, [128, "CLIFF DETECTED"]
```

```
PAUSE 5
```

```
PAUSE 20
```

```
LOOP
```

```
'Check for IR Sensor 1 and 2 HIGH
```

```
' Left Servo Move Pulse Value
```

```
' Right Servo Move Pulse Value
```



# How to interface with User?

Monitor the statuses of wheelchair

- Forward
- Back
- Right
- Left
- Stationary
- Cliff Detected etc..







# Safety

Two fingers movement  
(here 3 and 4) will stop the  
motion of wheelchair and  
put it in suspended mode.

```
IF (fs3 < 450) AND (fs4 < 450) THEN 'Stop switch
DO
IF(fs2 < 450) AND (fs1 < 450) THEN 'Reset the stop switch
  SEROUT lcd, 84, [12]
  PAUSE 5
  SEROUT lcd, 84, [128,"Reset Cleared"]
  PAUSE 5
  DEBUG "reset cleared"
  GOTO main
ELSE
  DEBUG "reset"
  SEROUT lcd, 84, [12]
  PAUSE 5
  SEROUT lcd, 84, [128,"STOP! Switch"]
  PAUSE 5
  GOSUB f3
  GOSUB f4
ENDIF
LOOP
ENDIF
```



# Bill of Material

Bill of Material for Mechatronics Term Project				
Item	Cost per Item	No of Item	Total	Mass Production
Flex Sensor	7.49	4	29.96	20
IR Sensor	12	2	24	16
Wires	3	3	9	3
Ultrasonic	15	1	15	12
Boeobot Chasis	59	1	59	40
Total			136.96	91



# Advantage and Disadvantage

## - Pros

- People who have RSI on their wrist can control wheelchair easily
- Wearable
- It can use as little as two and at most four fingers so the system can be customized for different users.

## - Cons

- The glove is wired so it is clunky and obtrusive



# References

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**THANK YOU**