

# Lecture 14

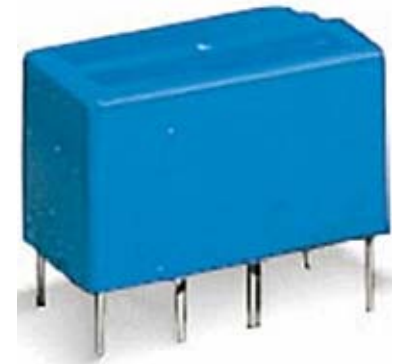
## Relays

# Relays



Mechanical relay

- Relays are electrically actuated switches
  - Mechanical relays
  - Reed relays
  - Solid-state relays



Miniature relay



Reed relay

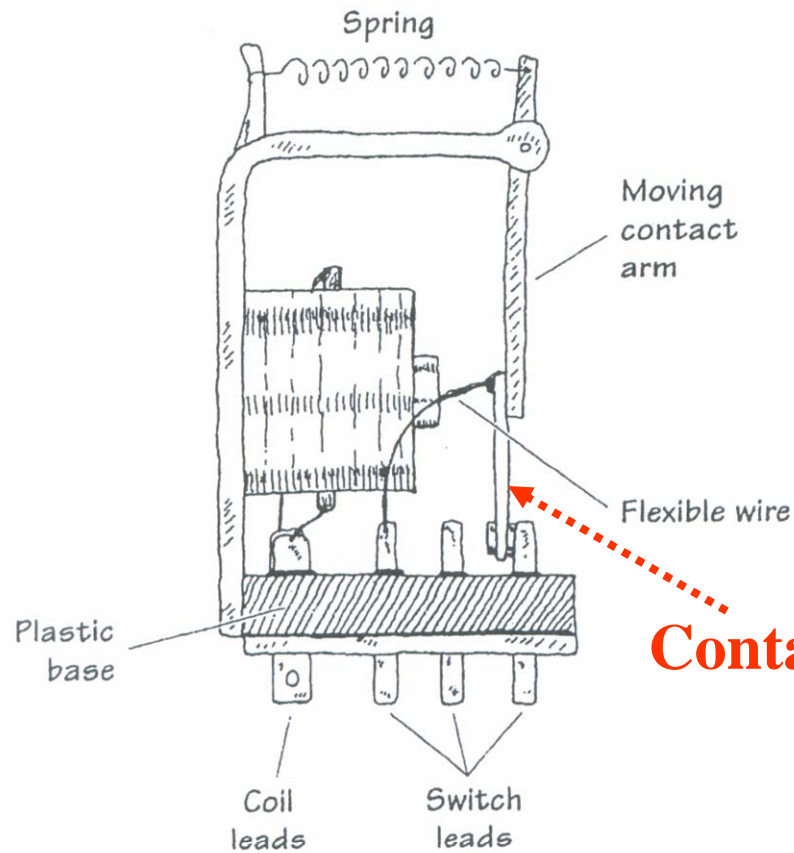
- A relay consists of an electromagnetic coil and one or more pairs of contacts



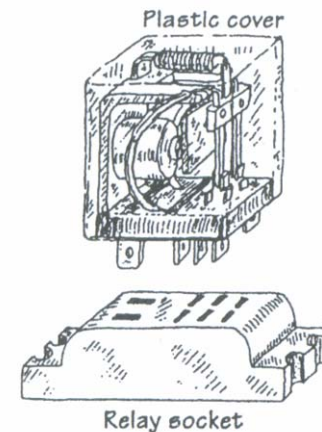
Solid-State relay

# Mechanical Relays

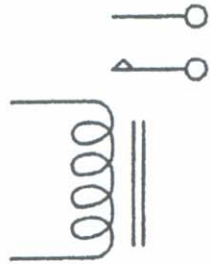
- Designed for high currents
  - Typically from 2A to 15A
- Relatively slow switching
  - 10ms to 100ms



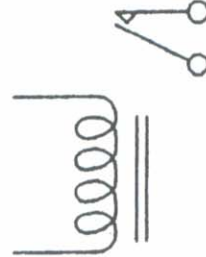
**Contact switch**



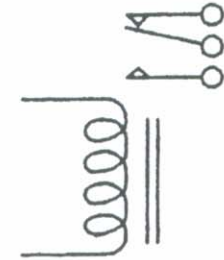
# Common Symbols for Relays



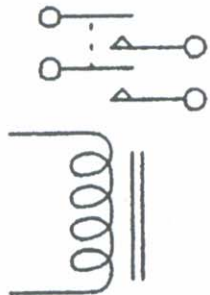
SPST (normally open)  
Single Pole, Single Throw



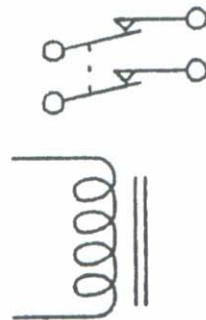
SPST (normally closed)



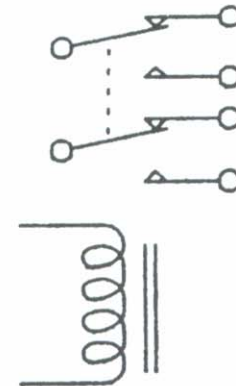
SPDT



DPST (normally open)



DPST (normally closed)

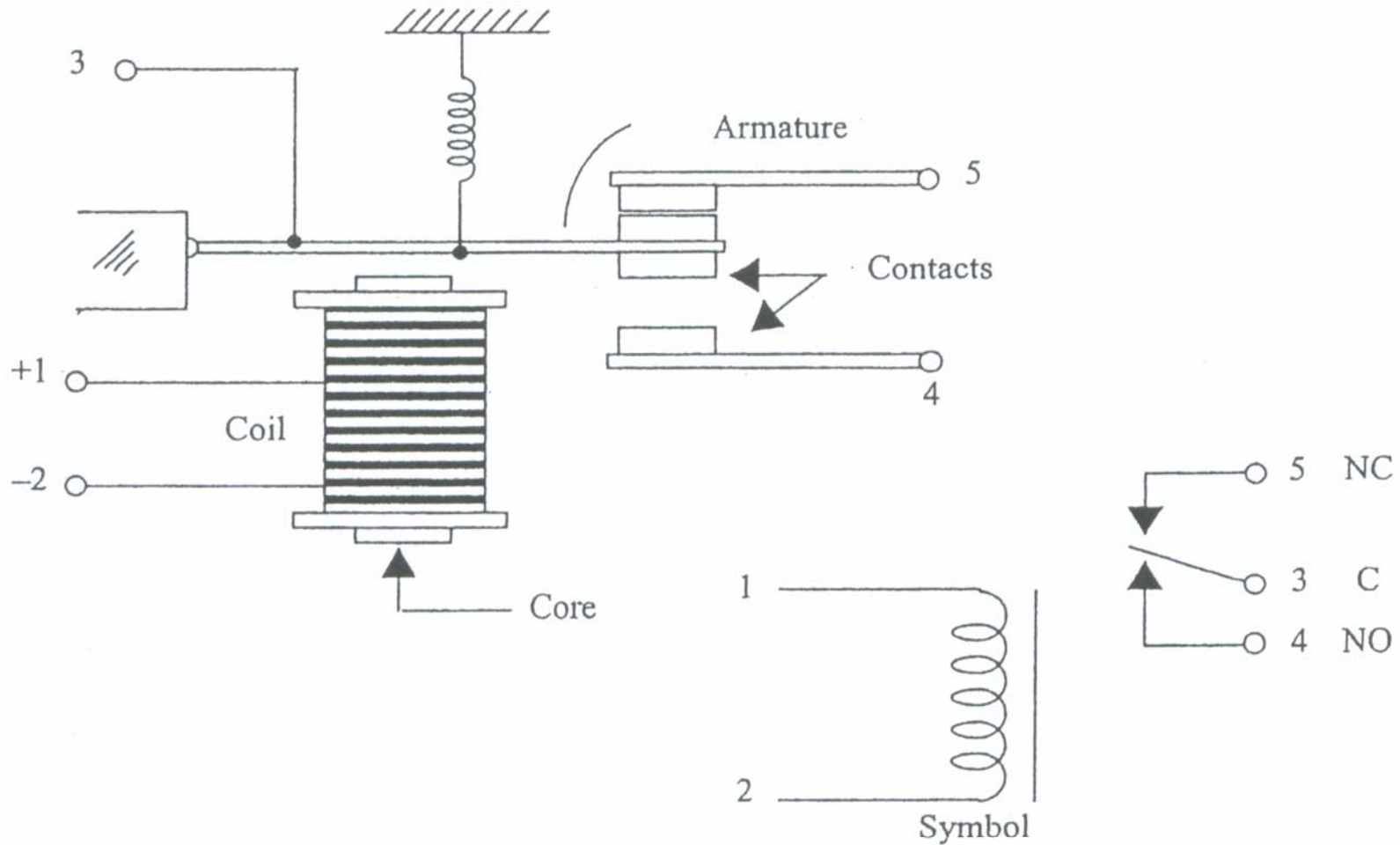


DPDT

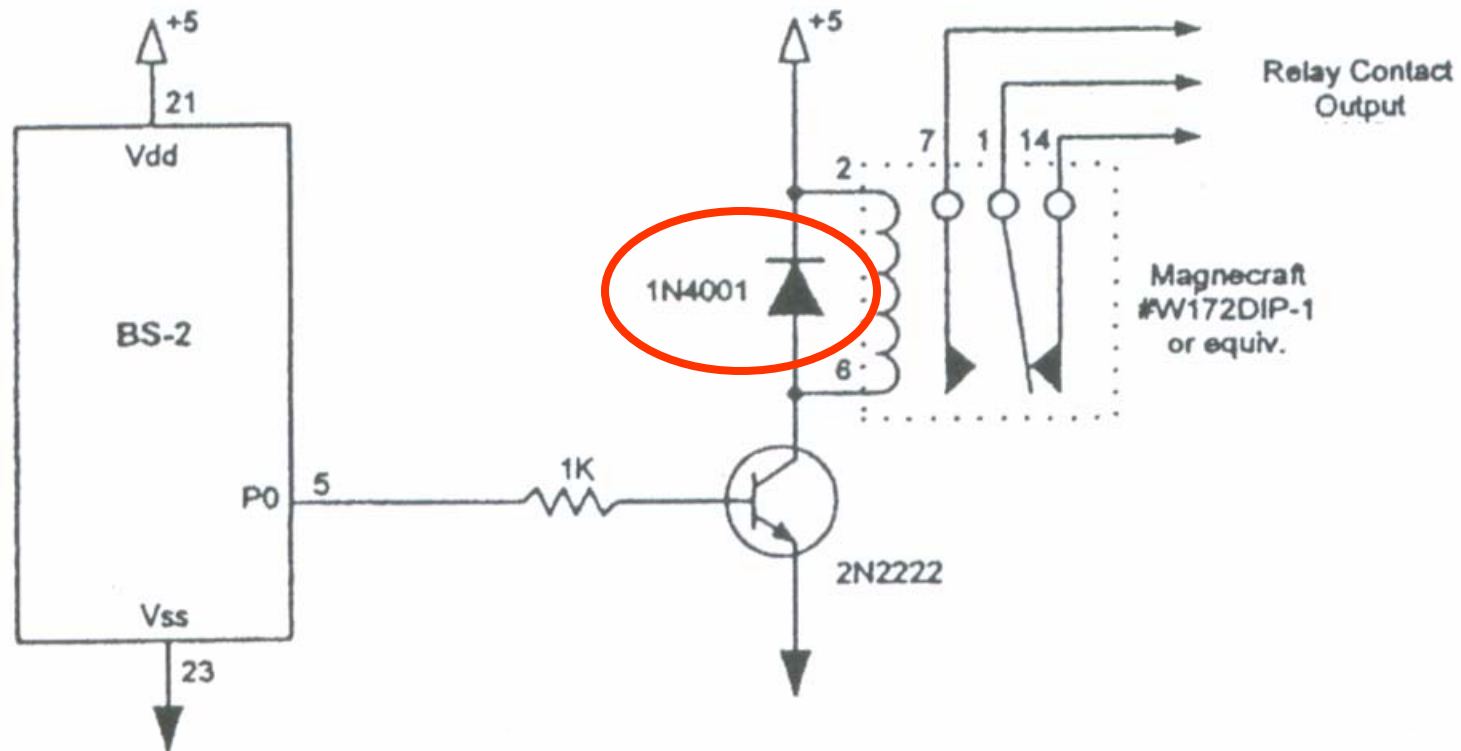
# Notes About Relays

- To make a relay change states, the voltage across of its magnetic coil should be at least within  $\pm 25$  percent of the relay's specified control voltage rating ( $V_c \pm 0.25 \times V_c$ )
- Sudden changes in current will create voltage spike, to avoid this is to use transient suppressors

# Electromechanical Relay

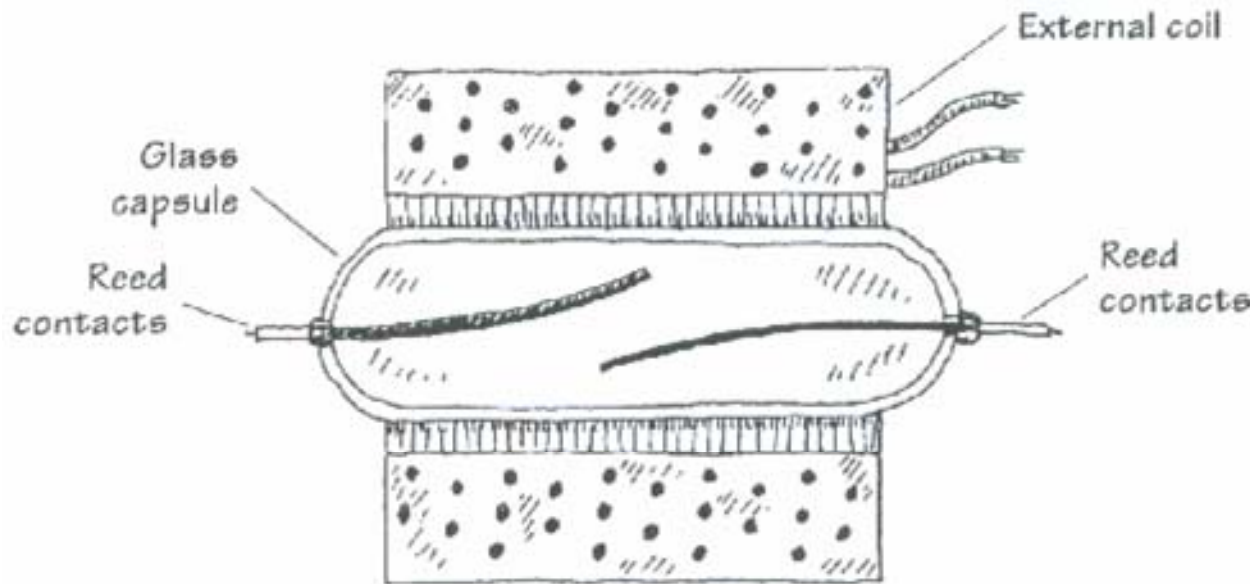


# Relays with BS2

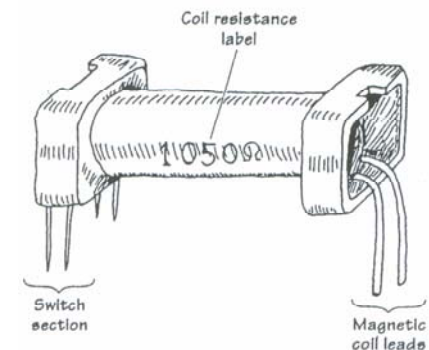


Using an NPN transistor to drive a relay

# Reed Relays



- Designed for moderate currents
  - Typically from 500mA to 1A
- Moderately fast switching
  - 0.2ms to 2ms

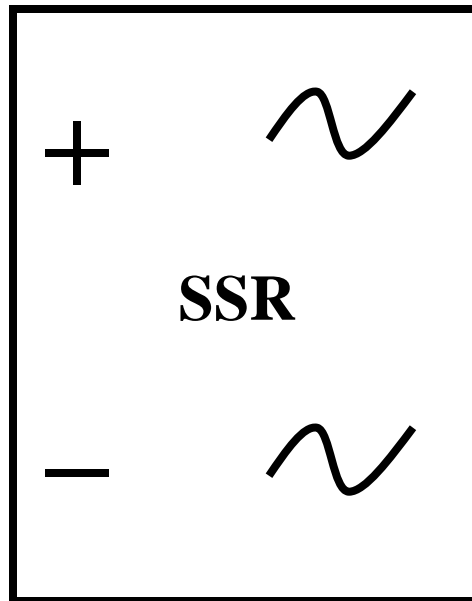




# Description

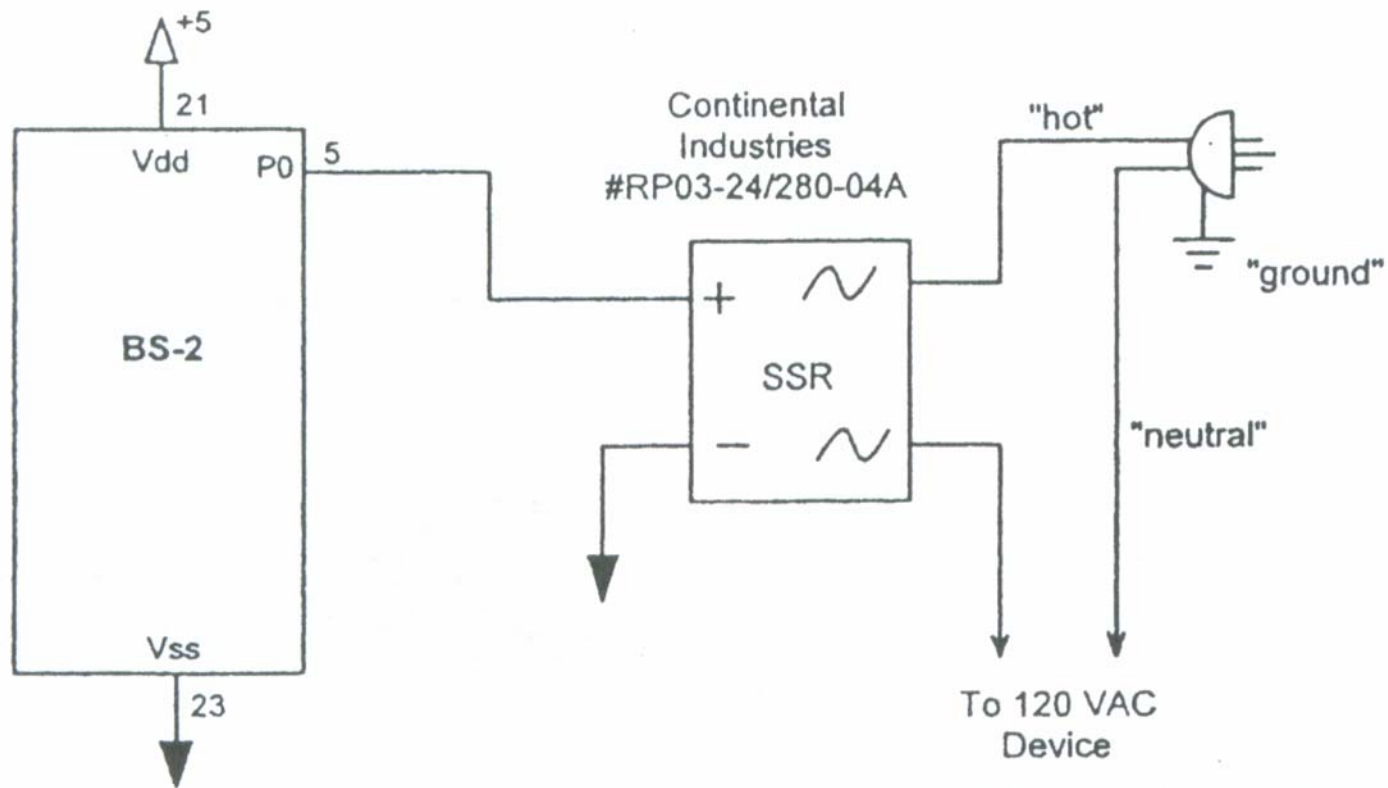
- Contains two magnetizable and electrically conductive reeds
- Magnetic field will cause the contacts to pull together

# Solid State Relays



- Contains no moving parts
- Wide range of current ratings
  - from a few  $\mu\text{A}$  to 100A
- Extremely fast switching
  - 1 to 100 ns

# Solid State Relay with AC



**Extremely caution with 120V AC !!**

# Relay Experiments

Experiments	Chapters
What's micro controller	
Basic A and D	
Earth measurements	
Robotics	
StampWorks	
Others	

# Lecture 15

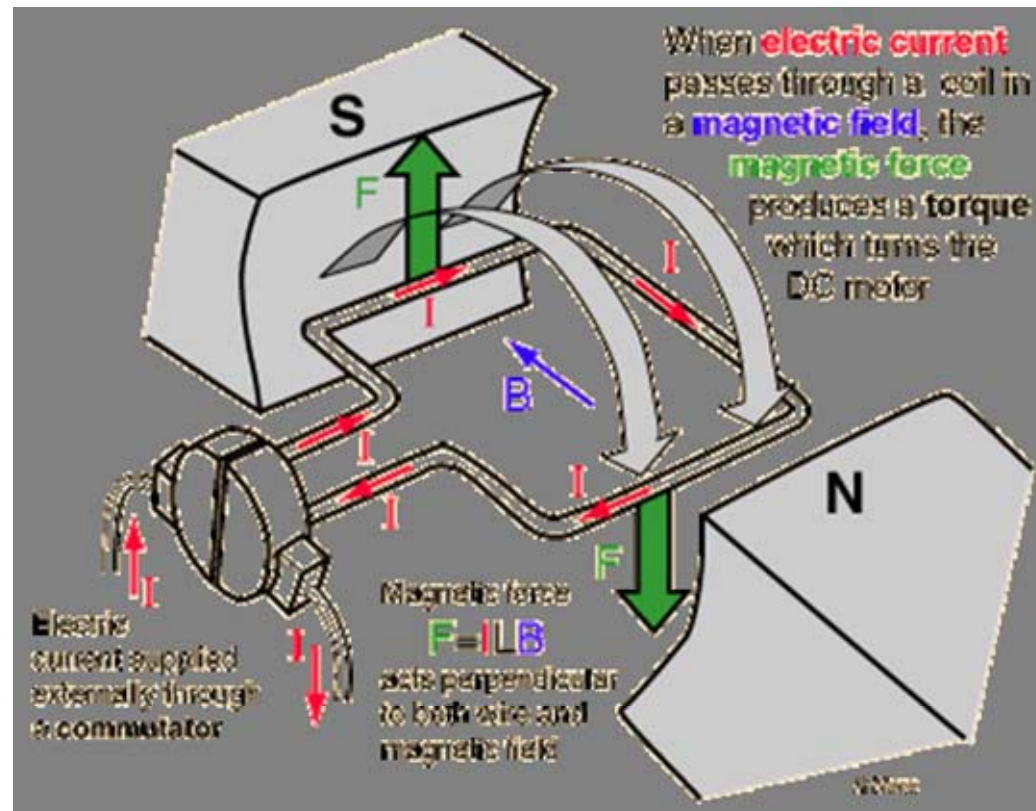
## DC Motor

# DC Motor

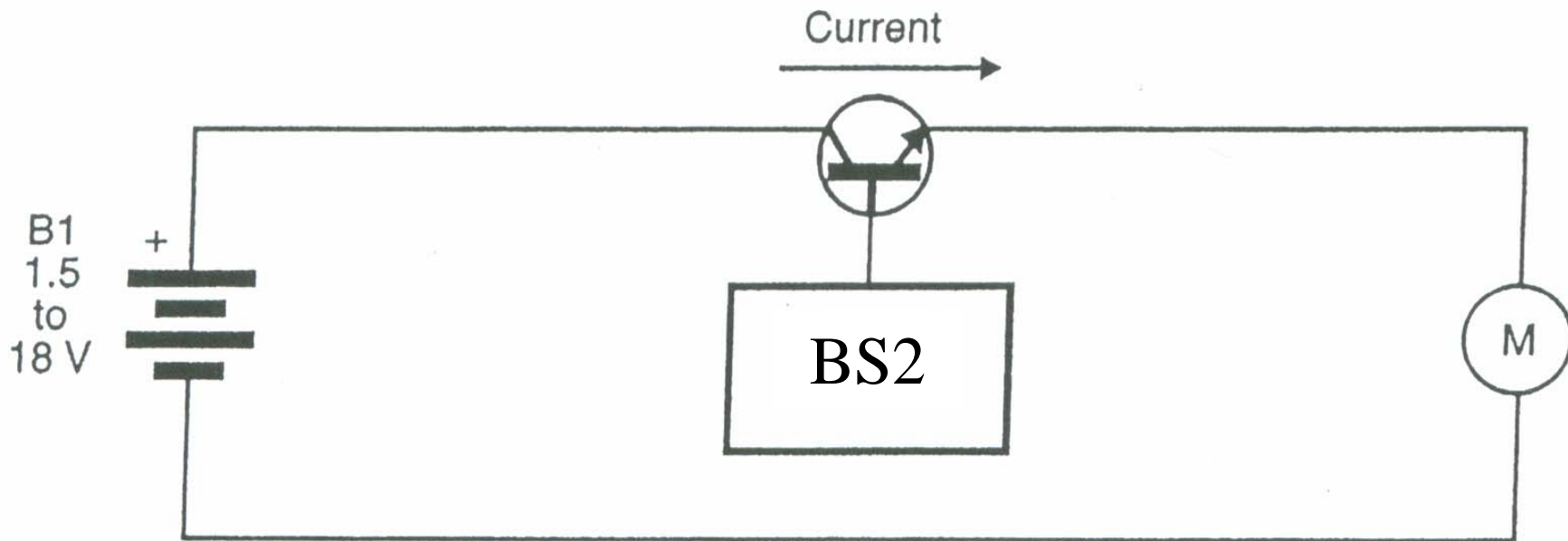


- DC motors are
  - Simple two-lead
  - Electrically controlled
- The voltage range of the DC motor is
  - 1.5V ~ 48V

# DC Motor: How It Works



# Turning a DC Motor On/Off

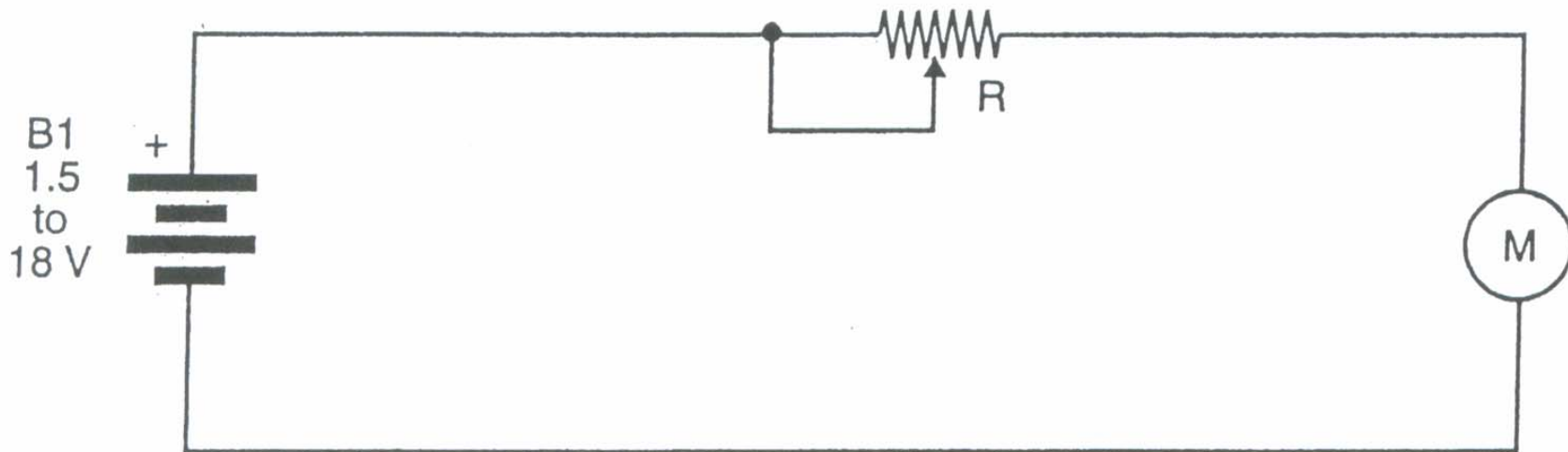




# DC Motor Speed Control 1

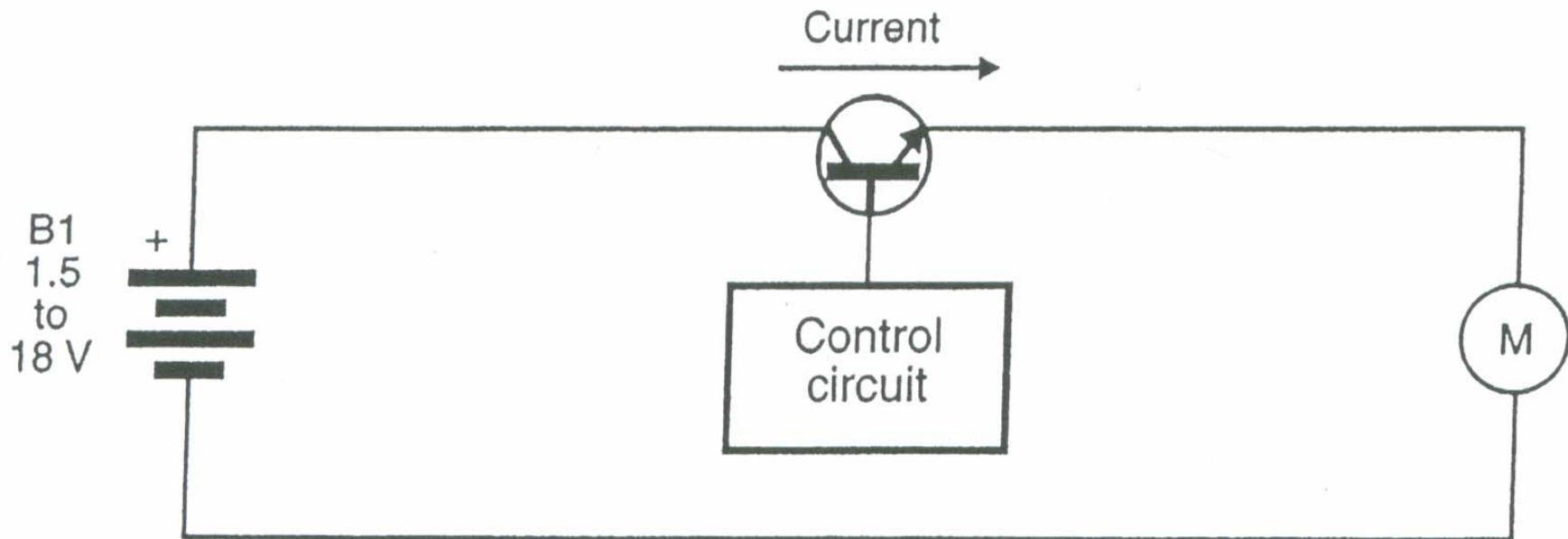
- When the voltage applied to a DC motor
  - Lower than nominal voltage → Motor runs slower
  - Higher than nominal voltage → Motor runs faster
- Linear control
  - Connect a potentiometer in series with motor
  - Use a transistor (BJT/FET) as a variable resistor

# DC Motor Speed Control 2



Linear control using a potentiometer in series with motor

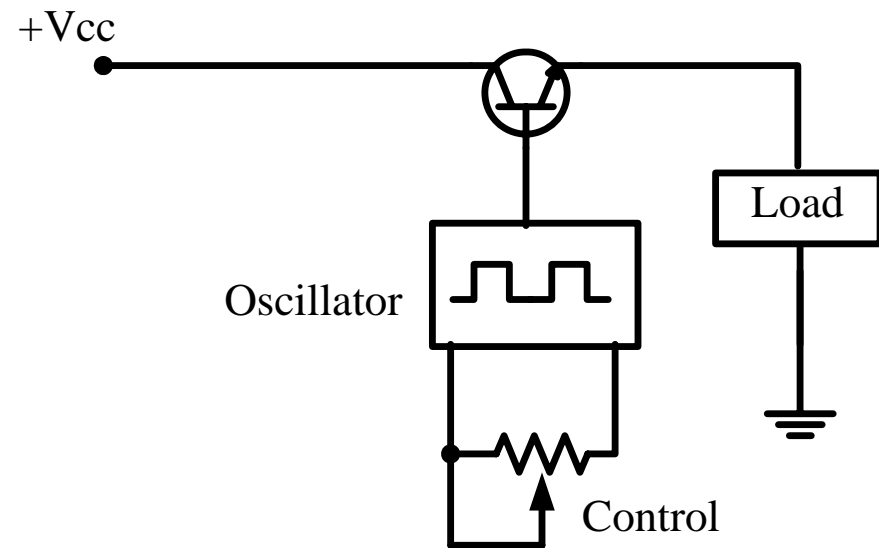
# DC Motor Speed Control 3



Linear control using a bipolar transistor

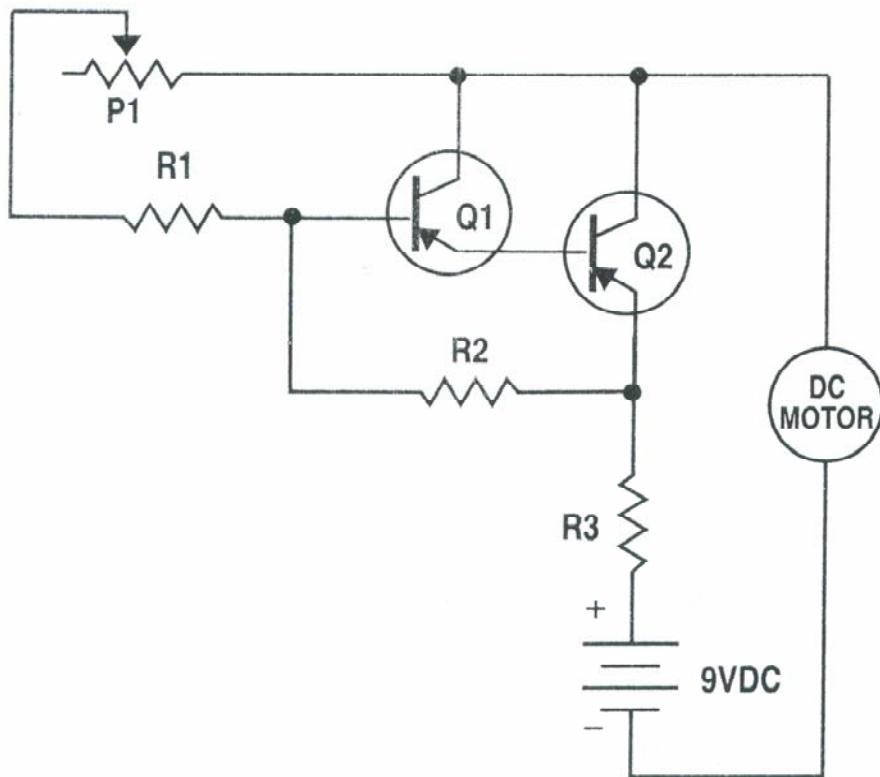
# Pulse Width Modulation 1

- An efficient method to deliver controlled amount of power to loads
- Use square voltage pulses to power a load
- The amount of power deliver to load depends on the duration of each pulse



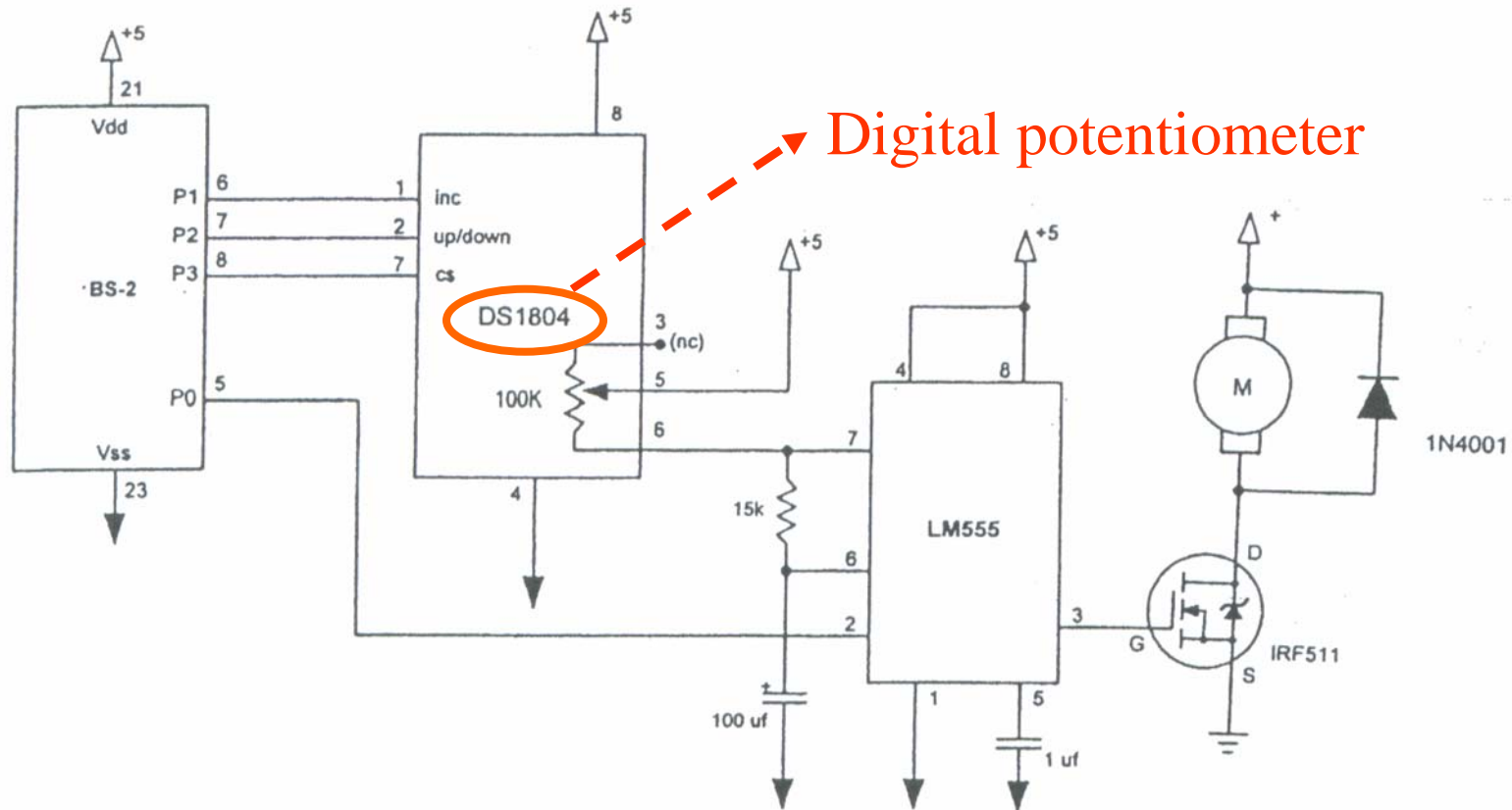
Basic PWM control

# Pulse Width Modulation 2



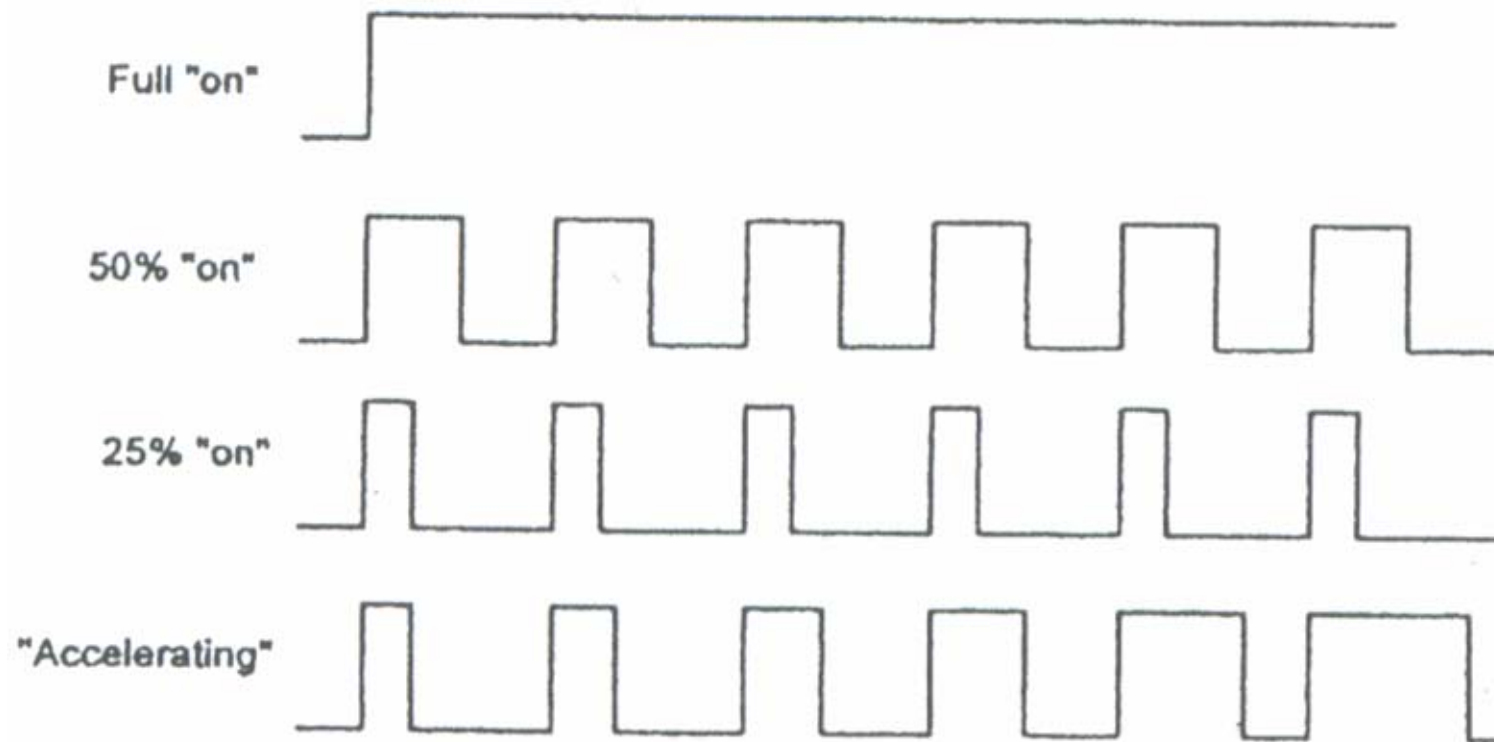
P1	50k Potentiometer
M1	DC Motor
Q1	PNP Transistor
Q2	PNP Transistor
R1	1k $\Omega$
R2	15k $\Omega$
R3	12 $\Omega$

# Pulse-Width-Modulation 3



Controlling on-time duration of a DC motor

# Pulse-Width-Modulation 4



PWM